



# MOLECULAR PROPERTY SPECTROMETER™ (MPS™) METHANE GAS SENSOR USER MANUAL

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## 1. How the MPS Methane Gas Sensor Works

The MPS Methane Gas Sensor is a smart sensor with built-in environmental compensation that detects and quantifies methane gas. It is robust, extremely poison-resistant, and comes factory-calibrated. Sensor readings are output on a standard digital bus or analog output.

The MPS transducer is a micro-machined membrane with an embedded Joule heater and resistance thermometer. The MEMS transducer is mounted on a PCB and packaged inside a filtered enclosure that is permeable to ambient air. Presence of a methane causes changes in the thermodynamic properties of the air/gas mixture; these properties are measured by the transducer and processed by patent-pending algorithms to report an accurate concentration.

## 2. Communicating with the MPS Methane Gas Sensor

This section describes the software interface requirements for the MPS Methane Gas Sensor and will be useful to system integrators when designing the sensor assembly into a final product.

The preferred method of communicating with the sensor is over the serial interface using the UART (Universal Asynchronous Receiver/Transmitter) protocol. Section 2.1 provides the necessary information for communicating using UART.

### 2.1. Serial (UART) Communication

Communication with the system over the serial interface (UART) will allow an external user or system to execute the commands provided in the Command Table in Section 2.1.5. Users may also refer to the Command Descriptions in Section 2.1.6 for usage descriptions.

Serial connection parameters:

Parameter	Size
Baud Rate	38400
Data Size	8 bits
Parity	None
Stop Bit	1 bit

#### 2.1.1. Data Representation

All integer values (16 bits or 32 bits) are represented in Little Endian format (LSB first). This means when an integer is transmitted on the serial interface, the least significant byte (LSB) is transmitted first and the most significant byte (MSB) is transmitted last.

Floating point numbers are represented in IEEE 754 format.

#### 2.1.2. Protocol Specification

Communication to and from the MPS Methane Gas Sensor is made up of “packets.” The communication paradigm is that of “request” and “reply.” An external host sends a “request” packet

to the sensor. The sensor returns a “reply” packet to the external host. A packet consists of a fixed size “header” and a variable length “payload.” It is possible for a packet to have no payload (length of zero) where a packet contains only a header. The payload, if any, typically consists of “parameters” for a request or “result” for a reply. Even when a reply does not contain any result, a reply is still sent with the header as an acknowledgement of the request.

## Command Request

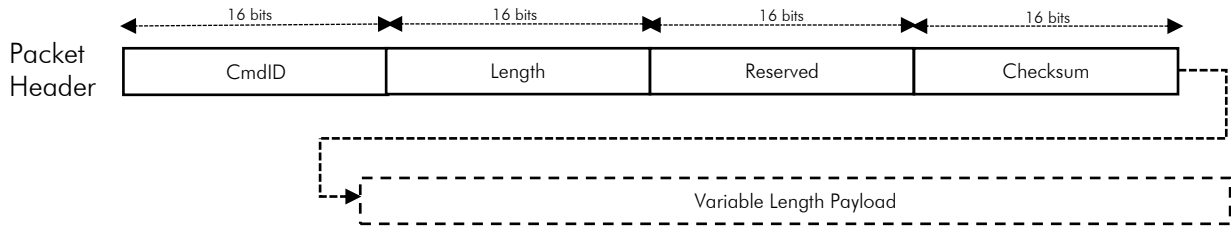


Figure 1: Request Packet Structure

The Request Packet (Figure 1) consists of the following fields:

Field	Size	Description
CmdID	2 Bytes	Command ID of this request (see Command Table in Section 2.1.5). Although CmdID uses only 1 byte, it is extended to 2 bytes in the Request Header for alignment purposes.
Length	2 Bytes	Length of the Payload (0 if no payload)
Reserved	2 Bytes	Reserved for future use (zero filled)
Checksum	2 Bytes	Checksum of the entire packet
Variable Length Payload	variable	Command parameters for this request

## Command Reply

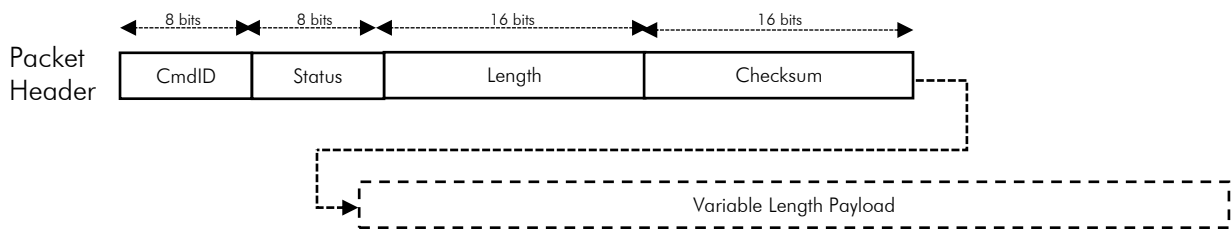


Figure 2: Reply Packet Structure

The Reply Packet (Figure 2) consists of the following fields:

Field	Size	Description
CmdID	1 Byte	Command ID (should match the original request)
Status	1 Byte	Return status of the request
Length	2 Bytes	Length of the Payload (0 if no payload)
Checksum	2 Bytes	Checksum of the entire packet
Variable Length Payload	variable	Command parameters for this request

The Status field consists of the following possible return values:

Fault	Fault Message	Explanation	Concentration Output (ppm)	User action
0x00	OK	MPS is operating normally and has no errors	Normal	None
0x01	CRC_FAILED	Transmitted data failed checksum	N/A	Verify checksum calculation is correct. See Section 2.1.3.
0x02	BAD_PARAM	Illegal or bad parameters specified	N/A	Verify parameter given in command is correct.
0x03	EXE_FAILED	Execution of command failed	N/A	Contact support.
0x04	NO_MEM	Insufficient memory for operation	N/A	Contact support.
0x05	UNKNOWN_CMD	Unknown Command ID specified	N/A	Verify Command ID is correct. See Section 2.1.5.
0x07	INCOMPLETE_COMMAND	Incomplete or truncated command	N/A	Verify entire packet header and payload (if any) is fully sent.
0x20	HW_ERR_AO	Analog out malfunction (only if AO functionality enabled)	-100 ppm	Contact support.
0x22	HW_ERR_VREF	Voltage out of range	-100 ppm	Supply 3.3-5.0 $\pm$ 5% VDC. If this error persists for more than 5 cycles, this error will latch until the sensor is power cycled and supplied correct voltage
0x24	HW_ENV_SNSR_MALFUNCTION	Environmental sensor malfunction	-100 ppm	Occurrence of this error will latch the sensor in this condition and no longer allow normal operation. Contact support.
0x25	HW_ERR_MCU_FLASH	Microcontroller error	-100 ppm	Contact support.
0x26	HW_SENSOR_INITIALIZATION	Sensor in initialization mode (10 cycles)	-100 ppm	Wait 10 cycles (~20 sec) for sensor to initialize.
0x32	HW_SENSOR_MALFUNCTION	Gas sensing element malfunction	-100 ppm	Contact support.

### 2.1.3. Checksum Calculation

The algorithm for checksum calculation is that of 16-bit CRC CCITT with start byte 0xFFFF. Checksum is computed over the entire packet (header and payload). The checksum field in the header is initialized with zeros before computing checksum. If there is no payload, checksum is computed against the header only. The following sample C code can be used to calculate the checksum for a buffer of a given size:

```
#include <stdlib.h>
#include <stdint.h>

static uint16_t crc_table[256] = {
    0x0000, 0x1021, 0x2042, 0x3063, 0x4084, 0x50a5, 0x60c6, 0x70e7,
    0x8108, 0x9129, 0xa14a, 0xb16b, 0xc18c, 0xd1ad, 0xe1ce, 0xf1ef,
    0x1231, 0x0210, 0x3273, 0x2252, 0x52b5, 0x4294, 0x72f7, 0x62d6,
    0x9339, 0x8318, 0xb37b, 0xa35a, 0xd3bd, 0xc39c, 0xf3ff, 0xe3de,
    0x2462, 0x3443, 0x0420, 0x1401, 0x64e6, 0x74c7, 0x44a4, 0x5485,
    0xa56a, 0xb54b, 0x8528, 0x9509, 0xe5ee, 0xf5cf, 0xc5ac, 0xd58d,
    0x3653, 0x2672, 0x1611, 0x0630, 0x76d7, 0x66f6, 0x5695, 0x46b4,
    0xb75b, 0xa77a, 0x9719, 0x8738, 0xf7df, 0xe7fe, 0xd79d, 0xc7bc,
    0x48c4, 0x58e5, 0x6886, 0x78a7, 0x0840, 0x1861, 0x2802, 0x3823,
    0xc9cc, 0xd9ed, 0xe98e, 0xf9af, 0x8948, 0x9969, 0xa90a, 0xb92b,
    0x5af5, 0x4ad4, 0x7ab7, 0x6a96, 0x1a71, 0x0a50, 0x3a33, 0x2a12,
    0xdbfd, 0xcbdc, 0xfbbf, 0xeb9e, 0x9b79, 0x8b58, 0xbb3b, 0xab1a,
    0x6ca6, 0x7c87, 0x4ce4, 0x5cc5, 0x2c22, 0x3c03, 0x0c60, 0x1c41,
    0xedae, 0xfd8f, 0xcdec, 0xddcd, 0xad2a, 0xbd0b, 0x8d68, 0x9d49,
    0x7e97, 0x6eb6, 0x5ed5, 0x4ef4, 0x3e13, 0x2e32, 0x1e51, 0x0e70,
    0xff9f, 0xefbe, 0xdfdd, 0xcffc, 0xbf1b, 0xaf3a, 0x9f59, 0x8f78,
    0x9188, 0x81a9, 0xb1ca, 0xa1eb, 0xd10c, 0xc12d, 0xf14e, 0xe16f,
    0x1080, 0x00a1, 0x30c2, 0x20e3, 0x5004, 0x4025, 0x7046, 0x6067,
    0x83b9, 0x9398, 0xa3fb, 0xb3da, 0xc33d, 0xd31c, 0xe37f, 0xf35e,
    0x02b1, 0x1290, 0x22f3, 0x32d2, 0x4235, 0x5214, 0x6277, 0x7256,
    0xb5ea, 0xa5cb, 0x95a8, 0x8589, 0xf56e, 0xe54f, 0xd52c, 0xc50d,
    0x34e2, 0x24c3, 0x14a0, 0x0481, 0x7466, 0x6447, 0x5424, 0x4405,
    0xa7db, 0xb7fa, 0x8799, 0x97b8, 0xe75f, 0xf77e, 0xc71d, 0xd73c,
    0x26d3, 0x36f2, 0x0691, 0x16b0, 0x6657, 0x7676, 0x4615, 0x5634,
    0xd94c, 0xc96d, 0xf90e, 0xe92f, 0x99c8, 0x89e9, 0xb98a, 0xa9ab,
    0x5844, 0x4865, 0x7806, 0x6827, 0x18c0, 0x08e1, 0x3882, 0x28a3,
    0xcb7d, 0xdb5c, 0xeb3f, 0xfb1e, 0x8bf9, 0x9bd8, 0xabbb, 0xbb9a,
    0x4a75, 0x5a54, 0x6a37, 0x7a16, 0x0af1, 0x1ad0, 0x2ab3, 0x3a92,
    0xfd2e, 0xed0f, 0xdd6c, 0xcd4d, 0xbdaa, 0xad8b, 0x9de8, 0x8dc9,
    0x7c26, 0x6c07, 0x5c64, 0x4c45, 0x3ca2, 0x2c83, 0x1ce0, 0x0cc1,
    0xef1f, 0xff3e, 0xcf5d, 0xdf7c, 0xaf9b, 0xbfba, 0x8fd9, 0x9ff8,
    0x6e17, 0x7e36, 0x4e55, 0x5e74, 0x2e93, 0x3eb2, 0x0ed1, 0x1ef0,
};

uint16_t crc_generate(uint8_t *buffer, size_t length, uint16_t startValue)
{
    uint16_t crc;
    uint8_t *p;
    int ii;

    crc = startValue;

    for(p = buffer, ii = 0; ii < length; ii++) {
```

```
    crc = (crc << 8) ^ crc_table[(crc >> 8) ^ *p];  
    p++;  
}  
  
return crc;  
  
}
```

For more information on how to use the above function, please look at the sample test program “Sample Code” located here: <https://nevedanano.com/downloads>

#### 2.1.4. Startup and Measurement Sequence

Figure 3 describes the recommended steps after powering on the sensor plus the measurement sequence for getting answer data. The major steps consist of the following:

- After powering on the sensor, wait for the sensor to boot up completely (~3 seconds).
- Verify communication channel by asking the sensor for version information.
  - Firmware version information can be used to determine if a new firmware is available for upgrade.
  - Protocol version can be used to determine available commands, answers or new data.
- Start measurement in “continuous” mode.
- Wait 2 seconds for the first measurement to complete.
- Get Answer.
- Repeat process to get answer at desired frequency.

The sensor initializes for the first 10 cycles after powering up. During this period, the sensor output is set to “-100 ppm”, the sensor status is set to HW\_SENSOR\_INITIALIZATION, and the sensor is not capable of reporting gas concentrations. Once initialization is complete, the sensor is ready to report gas concentrations, and the status is set to 0x00.

*Note: It takes approximately 2 seconds to calculate and complete a measurement. If multiple requests to read the Answer register (0x01) were made within a two-second window, one might get the same answer. This depends on whether a new measurement is calculated between multiple Answer requests. The MPS Cycle Count (“COUNT”) in the Answer Response is incremented after each measurement is calculated. Therefore, when processing an “answer,” one should compare the COUNT value in the answer against the COUNT value from the previous answer. If the COUNT value did not increment, this a repeated answer. If the COUNT value incremented, this is a new answer from the latest measurement cycle. When continuous measurement is stopped and restarted, the COUNT value resets to 1 with the first measurement.*



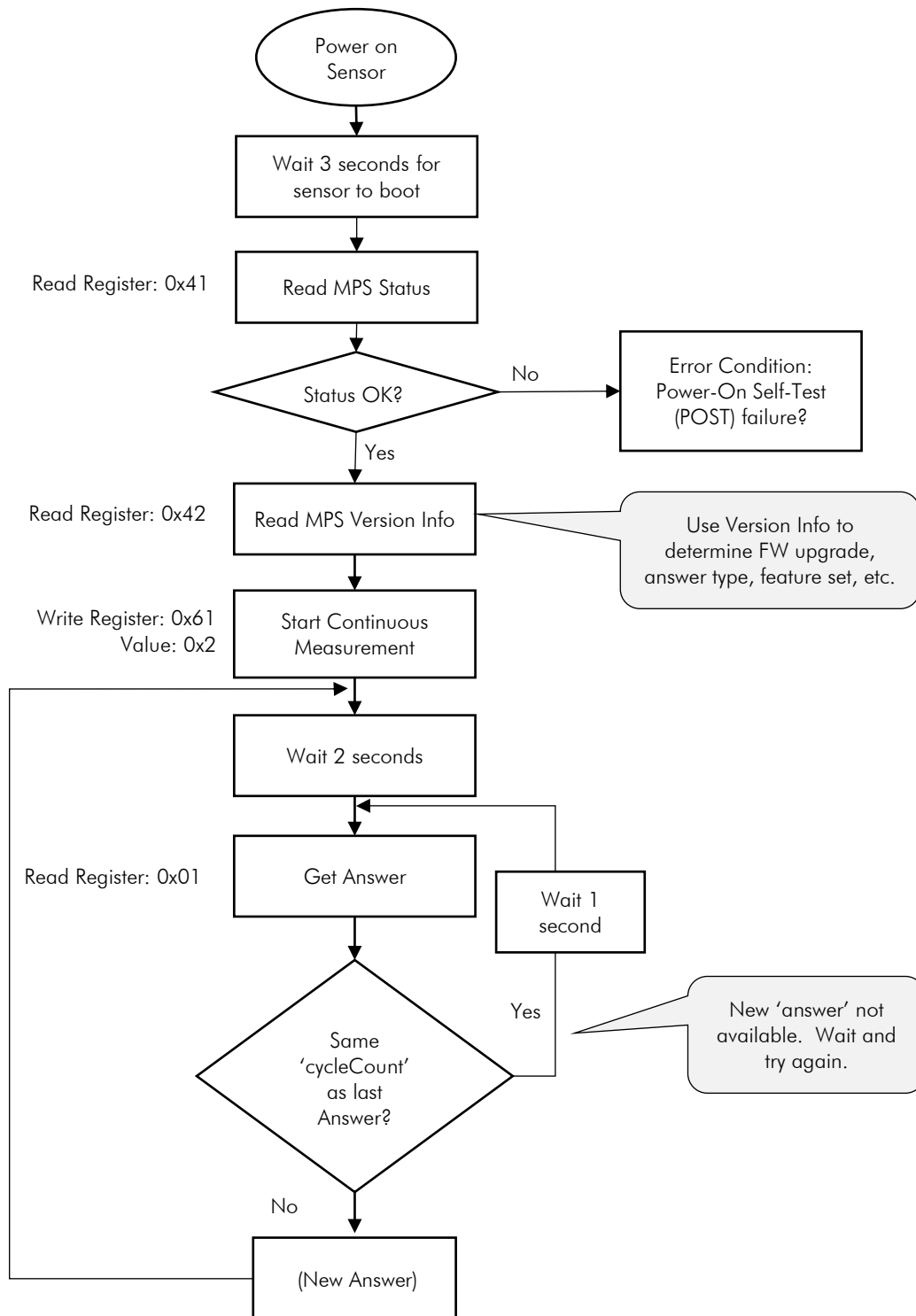
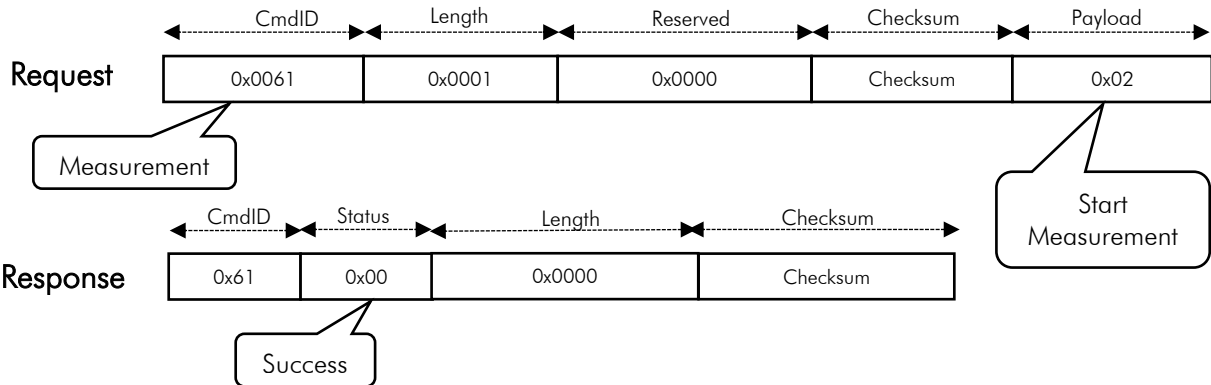


Figure 3: Startup and Measurement Sequence

Figure 4 describes sample Request and Response packets for the Perform Measurement and Get Answer Vector sequences.

## Perform Measurement



## Get Answer Vector

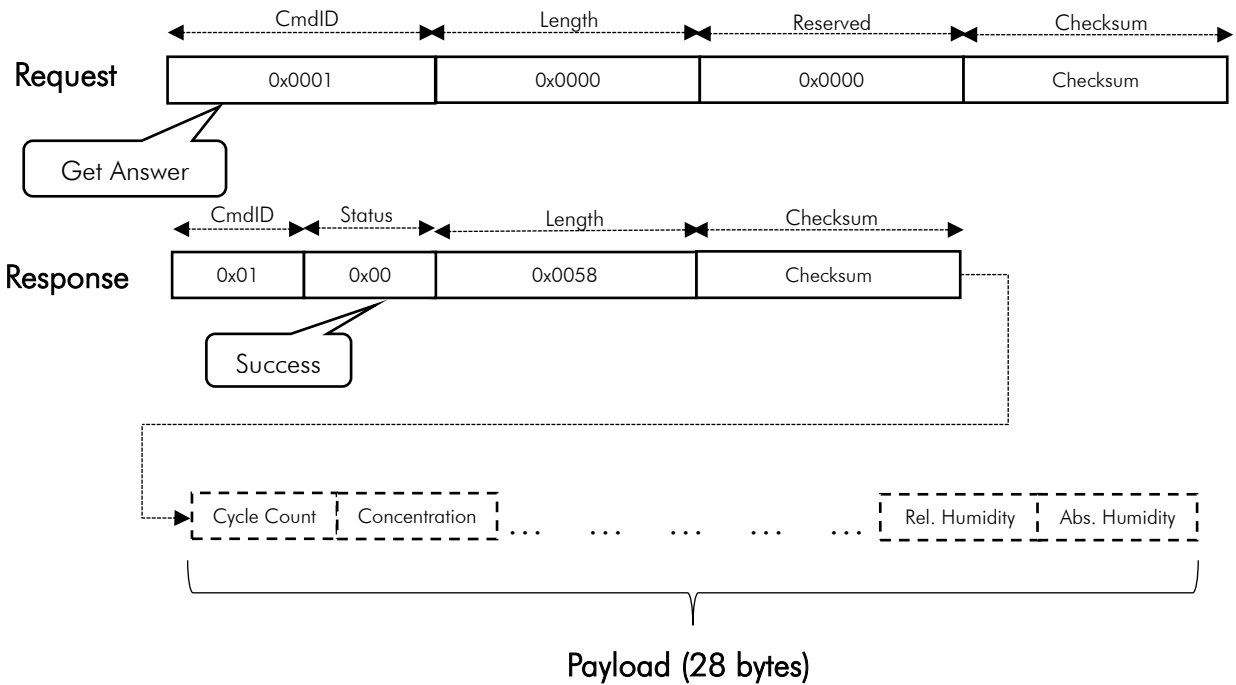


Figure 4: Sample Request and Response Packets for Performing Measurement and Get Answer Vector

### 2.1.5. Command Table

Hex Code	Command ID	Payload Length [bytes]	
		Request	Response
0x01	ANSWER	0	28
0x03	CONC	0	4
0x04	ID	0	4
0x09	ENG_DATA	0	84-128
0x21	TEMP	0	4
0x22	PRES	0	4
0x23	REL_HUM	0	4
0x24	ABS_HUM	0	4
0x41	STATUS	0	1
0x42	VERSION	0	8
0x43	SENSOR_INFO	0	68
0x61	MEAS	1	0
0x62	SHUT_DOWN	0	0

### 2.1.6. Command Descriptions

#### 1. Command 0x01 – ANSWER – Read Complete Answer

Description: Returns a complete answer in one read operation.

Parameters: N/A

Response:

CYCLE_COUNT	32-bit unsigned value. Cycle Number of this measurement (incremented after each measurement)
CONC	32-bit floating point value. Methane gas concentration [ppm]
ID	32-bit unsigned value. Gas ID. See “Command 0x04 – ID” for descriptions of Gas ID values.
TEMP	32-bit floating point value. Ambient temperature [°C]
PRESSURE	32-bit floating point value. Ambient pressure [kPa]
REL_HUM	32-bit floating point value. Ambient relative humidity [%RH]
ABS_HUM	32-bit floating point value. Ambient absolute humidity [ $\frac{g}{m^3}$ ]

#### 2. Command 0x03 – CONC – Read Methane Gas Concentration

Description: Returns methane gas concentration (ppm) as measured by the MPS.

Parameters: N/A

Response: CONC 32-bit floating point value. Methane gas concentration (ppm)

#### 3. Command 0x04 – ID – Read Gas ID

Description: Returns Gas ID as determined by the MPS.

Parameters: N/A

Response: ID 32-bit unsigned value. Gas ID.

ID	Description
0	No Gas
3	Methane
253	Unknown Gas
255	Over Range – Concentration greater than 1,500 ppm

#### 4. Command 0x09 – ENG\_DATA – Read Engineering Data

Description: Returns raw engineering (binary) data for analysis and debugging.

Parameters: N/A

Response: LENGTH                    32-bit unsigned value. Length of engineering data.  
 DATA                                Engineering data (80 to 124 bytes). Actual size of data is specified in the LENGTH field.

#### 5. Command 0x21 – TEMP – Read Temperature

Description: Returns the ambient temperature (°C) as reported by the integrated environmental sensor.

Parameters: N/A

Response: TEMP; 32-bit floating point value. Ambient temperature (°C).

#### 6. Command 0x22 – PRES – Read Pressure

Description: Returns the ambient pressure (kPa) as reported by the integrated environmental sensor.

Parameters: N/A

Response: PRESSURE; 32-bit floating point value. Ambient pressure (kPa).

#### 7. Command 0x23 – REL\_HUM – Read Relative Humidity

Description: Returns the ambient relative humidity (%RH) as reported by the integrated environmental sensor.

Parameters: N/A

Response: REL\_HUM 32-bit floating point value. Ambient relative humidity (%RH).

#### 8. Command 0x24 – ABS\_HUM – Read Absolute Humidity

Description: Returns the ambient absolute humidity ( $\frac{g}{m^3}$ ) as calculated by the MPS.

Parameters: N/A

Response: ABS\_HUM 32-bit floating point value. Ambient absolute humidity ( $\frac{g}{m^3}$ ).

#### 9. Command 0x41 – STATUS – Read MPS Status

Description: Returns the status of the MPS; refer to Sec. 2.1.2 for status descriptions.

Parameters: N/A

Response: STATUS 8-bit unsigned value. Status of MPS

## 10. Command 0x42 – VERSION – Read MPS Version Info

Description: Returns the software, hardware and protocol versions of the MPS.

Parameters: N/A

Response: SW\_VERSION 8-bit unsigned values. Version is W.X.Y.Z  
 HW\_VERSION 8-bit unsigned values. Version is W.X  
 PROTOCOL\_VERSION 8-bit unsigned values. Version is W.X

MPS Version Info																															
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32
SW Version W [7:0]								SW Version X [7:0]								SW Version Y [7:0]								SW Version Z [7:0]							
33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64
HW Version W [7:0]								HW Version X [7:0]								Protocol Version W [7:0]								Protocol Version X [7:0]							

## 11. Command 0x43 – SENSOR\_INFO – Read MPS Sensor Info

Description: Returns information about the sensor.

Parameters: N/A

Response: SERIAL\_NUM Sensor serial number. 32 bytes, zero-padded ASCII string.  
 SENSOR\_TYPE Sensor type. 32-bit unsigned integer. (Note: “MPS Methane Gas Sensor” sensor type = 0x05)  
 CAL\_DATE Date of last calibration. 16 bytes, zero-padded ASCII string. Format is MM/DD/YYYY.  
 MFG\_DATE Date of manufacture. 16 bytes, zero-padded ASCII string. Format is MM/DD/YYYY.

## 12. Command 0x61 – MEAS – Perform Measurement

Description: Sets the sensing mode (idle, single, or continuous) and “concentration unit” in the measurement.

Parameters: The parameter to the Measurement command is 1 byte in length but consists of two, 4-bit values: Concentration Unit (bits 7:4) and Mode (bits 3:0).

Measurement Value (Byte)	
Conc. Unit [7:4]	Mode [3:0]

The “concentration unit” (bits 7:4 of the measurement byte) is parts-per-million by volume (ppm); this is the unit that will be reported for commands 0x01 and 0x03.

Unit	Name	Description
0x0	PPM	Concentration reported in parts per million.

The measurement mode (bits 3:0 of the measurement byte) consists of the following possible values:

MODE	Name	Description
0x2	MPS_CONT	MPS operates in an autonomous, continuous mode
0x3	MPS_STOP	Stop measurement – no measurements are being taken

Response: N/A

### 13. Command 0x62 – SHUT\_DOWN – Shut down MPS

Description: Prepares the MPS for a shutdown by saving necessary data and states.

Parameters: N/A

Response: N/A

## 2.2. Sensor Analog Output Mode

The MPS Methane Gas Sensor can be factory-configurable to report gas concentrations via an analog signal that mimics the output of conventional catalytic bead flammable gas sensors. The analog output signal from the MPS Methane Gas Sensor is generated with a digital-to-analog converter. The standard analog output range, shown in Fig. 5, is 0.4 V (0 ppm) to 2.0 V (1,500 ppm), linearly increasing at  $0.00107 \frac{V}{ppm}$ . As with the digital communication mode, the MPS output concentration resolution is 0.685 ppm for analog outputs. Upon startup, the analog output pin may report between 0.75-1.75 V momentarily (<100 ms) during initialization.

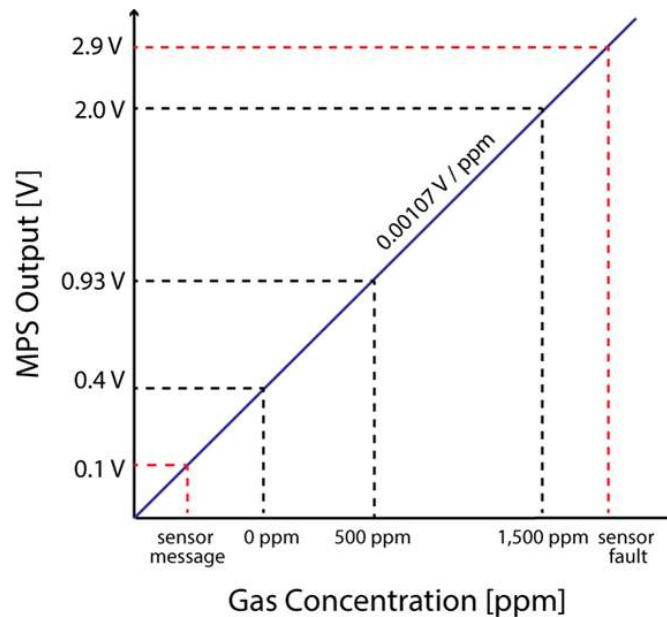


Figure 5: MPS Methane Gas Sensor output when configured in analog mode

When there is an error condition or special status, as reported by the sensor status field (outlined in Section 2.1.2.), the voltage level does not indicate gas concentration. Instead, the voltage is set to report an error or special status (see table below). Only critical statuses and messages that indicate the sensor's initialization sequence are conveyed to the user. The following table indicates the output voltage corresponding to each sensor message and critical status.

Status	Voltage [V]
HW_ERR_AO	2.9
HW_ERR_VREF	2.9
HW_ENV_SNSR_MALFUNCTION	2.9
HW_ERR_MCU_FLASH	2.9
HW_SENSOR_INITIALIZATION	0.1
HW_SENSOR_MALFUNCTION	2.9

### 3. Testing the MPS Methane Gas Sensor

The MPS Methane Gas Sensor measures molecular properties to determine the quantity of gas present in a sample, and automatically compensates out the effects of humidity, temperature and pressure. The best test setups are those which properly simulate real-world sensor operation.

### 4. Operating Conditions for the MPS Methane Gas Sensor

The table below provides a summary of standardized tests and test conditions to which the MPS Methane Gas Sensor has been subjected. The sensor has passed all of these tests by demonstrating normal gas detection performance both before and after each test.

Test	Specification	Summary of Test Conditions
High Temperature Operating	IEC 60068-2-2	1000 Hours @ 85°C
Low Temperature Operating	IEC 60068-2-1	1000 Hours @ -50°C
Drop	IEC 60068-2-31	1-meter drop onto concrete
Shock	IEC 60068-2-27	50G peak/11 ms half sine pulse, 3-axes (positive and negative pulses)
Vibration	IEC 60068-2-6	31Hz – 150 Hz (2G acceleration), 1 hour per axis, 3-axes
Sand/Dust	MIL-STD-810G Method 510.5	Sand: 150-600 $\mu\text{m}$ SiO <sub>2</sub> particle size, 23 m/s nom. velocity, 5 hours @ 70°C per axis, 3-axes Dust: Red China Clay, 1.5 m/s nom. velocity, 6 hours @ 70°C per axis, 3-axes
Poisoning	NevadaNano	1200 ppm-hours H <sub>2</sub> S (50 ppm for 24 hours) 100 ppm-hours HMDSO (10 ppm for 10 hours) 0.25 ppm-hours NO <sub>2</sub> (3 ppm for 5 minutes) 0.83 ppm-hours HCN (10 ppm for 5 minutes) 0.75 ppm-hours SO <sub>2</sub> (9 ppm for 5 minutes) 0.17 ppm-hours Cl <sub>2</sub> (2 ppm for 5 minutes) 4.17 ppm-hours NH <sub>3</sub> (50 ppm for 5 minutes)
EMC: Radiated Immunity	IEC/EN 61000-4-3	80 MHz – 2.7 GHz up to 10 V/m
EMC: Magnetic Immunity	IEC/EN 61000-4-8	30 A/m, 3-axes
EMC: Electrostatic Discharge	IEC/EN 61000-4-2	Up to 4kV on ground plane; up to 8kV corona discharge

#### 4.1. Hazardous Locations and System Integration

Integrating the MPS into intrinsically safe systems requires additional design consideration. Refer to the MPS Hazardous Locations User Guide (<https://nevadanano.com/downloads>) for information regarding certifications, protection concepts, and entity parameters.



## 5. Electromechanical Integration

The MPS Methane Gas Sensor critical dimensions are indicated in Figure 6 and the pinout in Figure 7. The mating receptacles are available in distribution, and can be found using Mill-Max P/N: 0384-0-67-80-23-27-10-0.

Note: the Analog Out pin, if unused, must be left unterminated as an "open" or "no-connect" in the system integrator's PCB design.

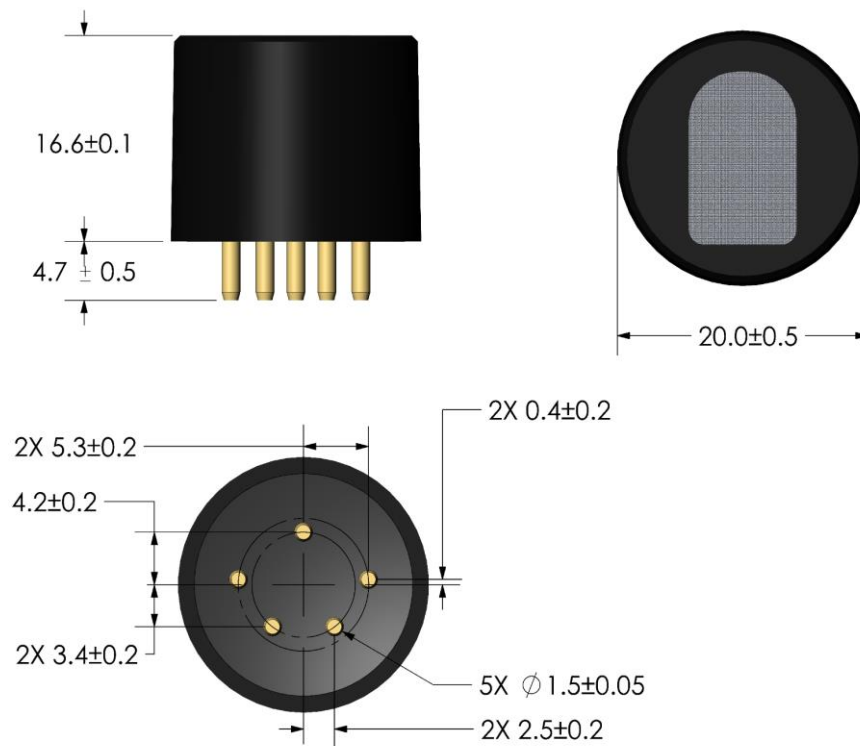


Figure 6: MPS Methane Gas Sensor critical dimensions (mm)

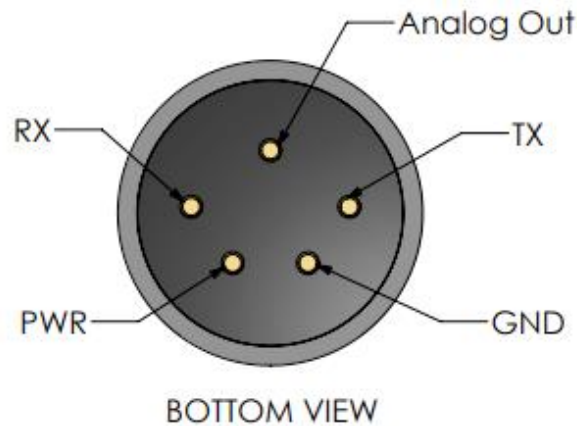


Figure 7: MPS Methane Gas Sensor electrical pin configuration

In powering the MPS sensor, the following criteria need to be met:

- Voltage range must be  $3.3\text{-}5.0\text{ V} \pm 5\%$
- Ripple and noise should not exceed 50 mV
- The supply must be capable of providing at least 35 mA without appreciable voltage drop
- The voltage rise rate at power up should be greater than  $250\ \mu\text{s}$  per volt from a cold start (that is, when powering up a sensor that has been off for more than 5 seconds)

Achieving the proper voltage rise rate can be accomplished using voltage regulators with “soft-start” capability, though added capacitance (less preferred), or by placing a series resistor between the voltage source and the MPS power pin.

If the voltage rise rate condition above is not met when powering up a sensor that has been off for more than 5 seconds, a small percentage of sensors may power up into a state in which they do not respond to commands or do not generate the proper analog output. If this occurs, shutting power off to the sensor for between 0.5 to 2 seconds and then immediately powering the sensor back on will cause the sensor to recover and power up normally, *even if the voltage rise rate condition above is not met.*



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